

2024 秋季本科时间序列

第 6 次作业答案

11 月 24 日

1. (a)

$$\mathbf{A}(\mathcal{L}) = \mathbf{I} - \Phi\mathcal{L} = \begin{bmatrix} 1 - 0.4\mathcal{L} & 0.2\mathcal{L} & -\mathcal{L} \\ -0.1\mathcal{L} & 1 - 0.7\mathcal{L} & -\mathcal{L} \\ 0 & 0 & 1 - 0.8\mathcal{L} \end{bmatrix}$$

(b)

$$\begin{aligned} \det \mathbf{A}(\mathcal{L}) &= (1 - 0.4\mathcal{L})(1 - 0.7\mathcal{L})(1 - 0.8\mathcal{L}) - 0.2\mathcal{L}(-0.1\mathcal{L})(1 - 0.8\mathcal{L}) \\ &= (1 - 0.8\mathcal{L})(1 - 1.1\mathcal{L} + 0.3\mathcal{L}^2) \\ &= 1 - 1.9\mathcal{L} + 1.18\mathcal{L}^2 - 0.24\mathcal{L}^3 \end{aligned}$$

$$\mathbf{A}^*(\mathcal{L}) = \begin{bmatrix} A_{11} & A_{21} & A_{31} \\ A_{12} & A_{22} & A_{32} \\ A_{13} & A_{23} & A_{33} \end{bmatrix}$$

$\mathbf{A}^*(\mathcal{L})$ 是 $\mathbf{A}(\mathcal{L})$ 的伴随矩阵, A_{ij} 是代数余子式, 可计算得到

$$A_{11} = \det \begin{bmatrix} 1 - 0.7\mathcal{L} & -\mathcal{L} \\ 0 & 1 - 0.8\mathcal{L} \end{bmatrix} = 1 - 1.5\mathcal{L} + 0.56\mathcal{L}^2$$

$$A_{12} = -\det \begin{bmatrix} -0.1\mathcal{L} & -\mathcal{L} \\ 0 & 1 - 0.8\mathcal{L} \end{bmatrix} = 0.1\mathcal{L} - 0.08\mathcal{L}^2$$

$$A_{13} = \det \begin{bmatrix} -0.1\mathcal{L} & 1 - 0.7\mathcal{L} \\ 0 & 0 \end{bmatrix} = 0$$

$$A_{21} = -\det \begin{bmatrix} 0.2\mathcal{L} & -\mathcal{L} \\ 0 & 1 - 0.8\mathcal{L} \end{bmatrix} = -0.2\mathcal{L} + 0.16\mathcal{L}^2$$

$$A_{22} = \det \begin{bmatrix} 1 - 0.4\mathcal{L} & -\mathcal{L} \\ 0 & 1 - 0.8\mathcal{L} \end{bmatrix} = 1 - 1.2\mathcal{L} + 0.32\mathcal{L}^2$$

$$A_{23} = -\det \begin{bmatrix} 1 - 0.4\mathcal{L} & 0.2\mathcal{L} \\ 0 & 0 \end{bmatrix} = 0$$

$$A_{31} = \det \begin{bmatrix} 0.2\mathcal{L} & -\mathcal{L} \\ 1 - 0.7\mathcal{L} & -\mathcal{L} \end{bmatrix} = \mathcal{L} - 0.9\mathcal{L}^2$$

$$A_{32} = -\det \begin{bmatrix} 1 - 0.4\mathcal{L} & -\mathcal{L} \\ -0.1\mathcal{L} & -\mathcal{L} \end{bmatrix} = \mathcal{L} - 0.3\mathcal{L}^2$$

$$A_{33} = \det \begin{bmatrix} 1 - 0.4\mathcal{L} & 0.2\mathcal{L} \\ -0.1\mathcal{L} & 1 - 0.7\mathcal{L} \end{bmatrix} = 1 - 1.1\mathcal{L} + 0.3\mathcal{L}^2$$

所以

$$A^*(\mathcal{L}) = \begin{bmatrix} 1 - 1.5\mathcal{L} + 0.56\mathcal{L}^2 & -0.2\mathcal{L} + 0.16\mathcal{L}^2 & \mathcal{L} - 0.9\mathcal{L}^2 \\ 0.1\mathcal{L} - 0.08\mathcal{L}^2 & 1 - 1.2\mathcal{L} + 0.32\mathcal{L}^2 & \mathcal{L} - 0.3\mathcal{L}^2 \\ 0 & 0 & 1 - 1.1\mathcal{L} + 0.3\mathcal{L}^2 \end{bmatrix}$$

$$A^{-1}(\mathcal{L}) = \frac{1}{\det A(\mathcal{L})} A^*(\mathcal{L})$$

$$= \frac{1}{1 - 1.9\mathcal{L} + 1.18\mathcal{L}^2 - 0.24\mathcal{L}^3} \begin{bmatrix} 1 - 1.5\mathcal{L} + 0.56\mathcal{L}^2 & -0.2\mathcal{L} + 0.16\mathcal{L}^2 & \mathcal{L} - 0.9\mathcal{L}^2 \\ 0.1\mathcal{L} - 0.08\mathcal{L}^2 & 1 - 1.2\mathcal{L} + 0.32\mathcal{L}^2 & \mathcal{L} - 0.3\mathcal{L}^2 \\ 0 & 0 & 1 - 1.1\mathcal{L} + 0.3\mathcal{L}^2 \end{bmatrix}$$

(c)

$$\begin{aligned}P(z) &= \det \mathbf{A}(z) \\&= 1 - 1.9z + 1.18z^2 - 0.24z^3 \\&= -0.02(z - 2)(4z - 5)(3z - 5)\end{aligned}$$

令 $P(z) = 0$ 得 $z_1 = 2, z_2 = \frac{5}{4}, z_3 = \frac{5}{3}$, 均满足 $z_i > 1$, 即三个零点均在单位圆外, \mathbf{X}_t

满足平稳性

(d) 特征值 λ 满足 $\det(\Phi - \lambda \mathbf{I}) = 0$

$$\begin{aligned}\det(\Phi - \lambda \mathbf{I}) &= \det \begin{bmatrix} 0.4 - \lambda & -0.2 & 1 \\ 0.1 & 0.7 - \lambda & 1 \\ 0 & 0 & 0.8 - \lambda \end{bmatrix} \\&= (0.4 - \lambda)(0.7 - \lambda)(0.8 - \lambda) + 0.02(0.8 - \lambda) \\&= -\lambda^3 + 1.9\lambda^2 - 1.18\lambda + 0.24 \\&= 0\end{aligned}$$

解得 $\lambda_1 = \frac{1}{2}, \lambda_2 = \frac{4}{5}, \lambda_3 = \frac{3}{5}$, 所以 $\lambda_i z_i = 1$, 即 z_i 与 λ_i 互为倒数, 对于 $i = 1, 2, 3$

均成立